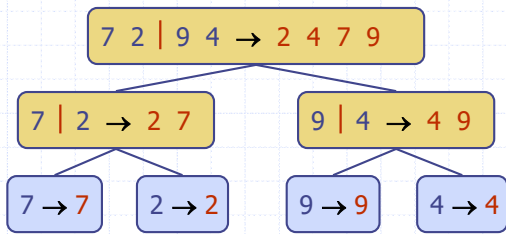


Merge Sort



1

We will look at this table later ...

Algorithm	Time	Notes
selection-sort	$O(n^2)$	<ul style="list-style-type: none"> slow in-place for small data sets (< 1K)
insertion-sort	$O(n^2)$	<ul style="list-style-type: none"> slow in-place for small data sets (< 1K)
heap-sort	$O(n \log n)$	<ul style="list-style-type: none"> fast in-place for large data sets (1K — 1M)
merge-sort	$O(n \log n)$	<ul style="list-style-type: none"> fast sequential data access for huge data sets (> 1M)

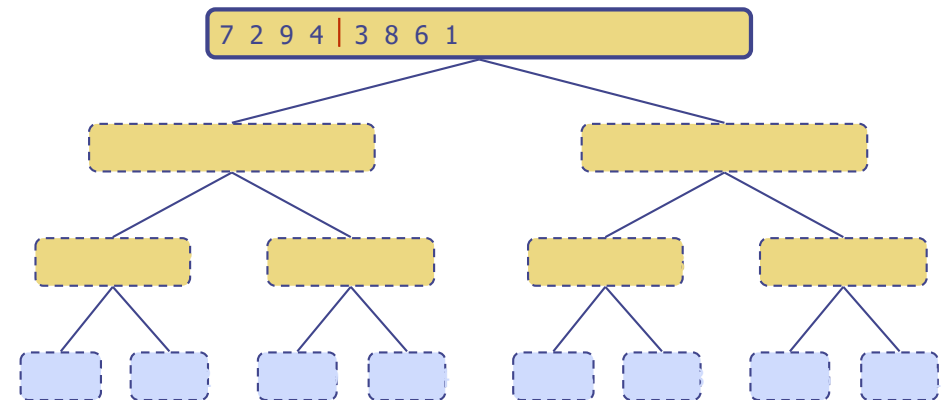
2

New things that we will learn from this part

- ◆ Divide-and-Conquer rationale
- ◆ Complexity analysis based on recurrence relation

Execution Example

- ◆ Partition

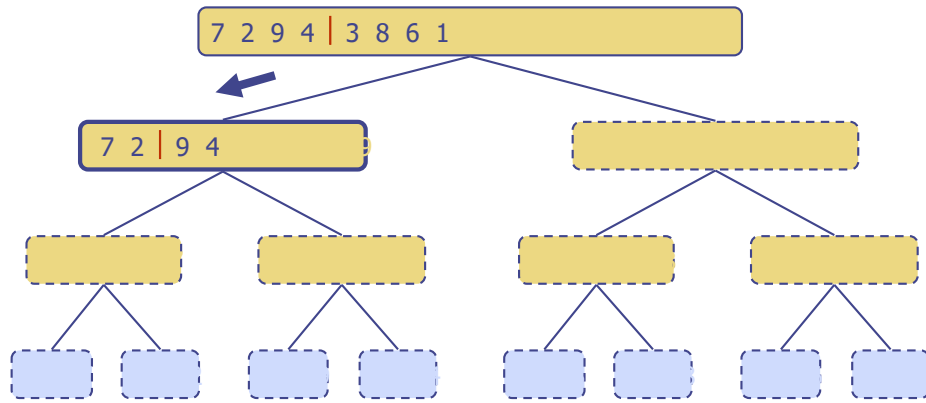


3

4

Execution Example (cont.)

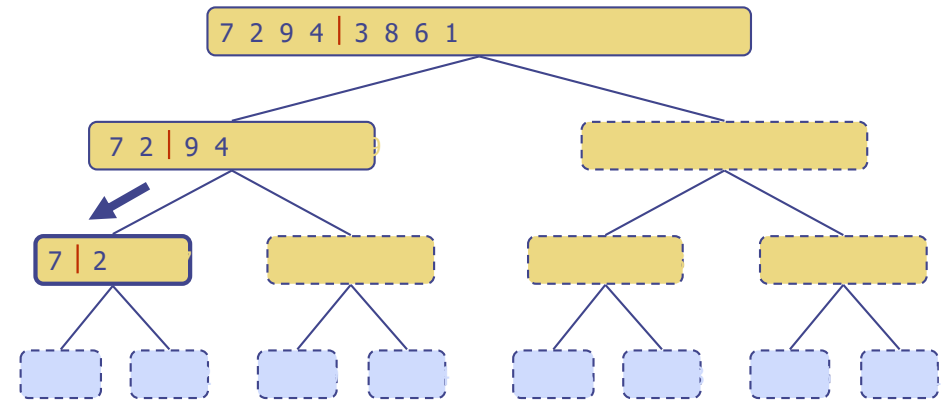
◆ Recursive call, partition



5

Execution Example (cont.)

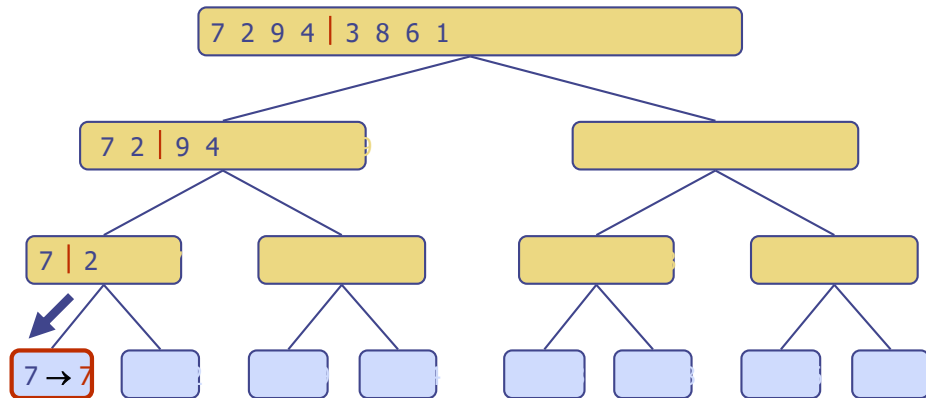
◆ Recursive call, partition



6

Execution Example (cont.)

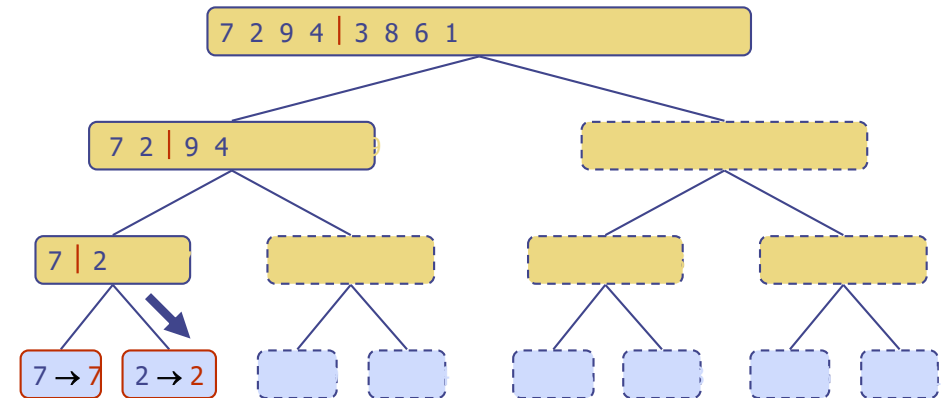
◆ Recursive call, base case



7

Execution Example (cont.)

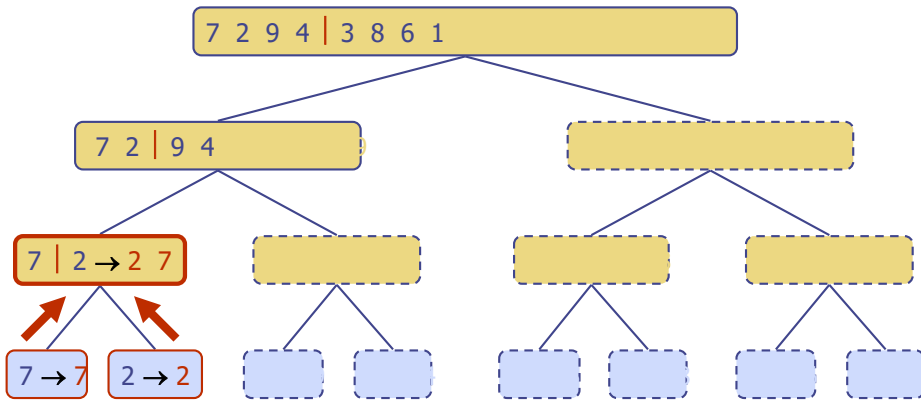
◆ Recursive call, base case



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Execution Example (cont.)

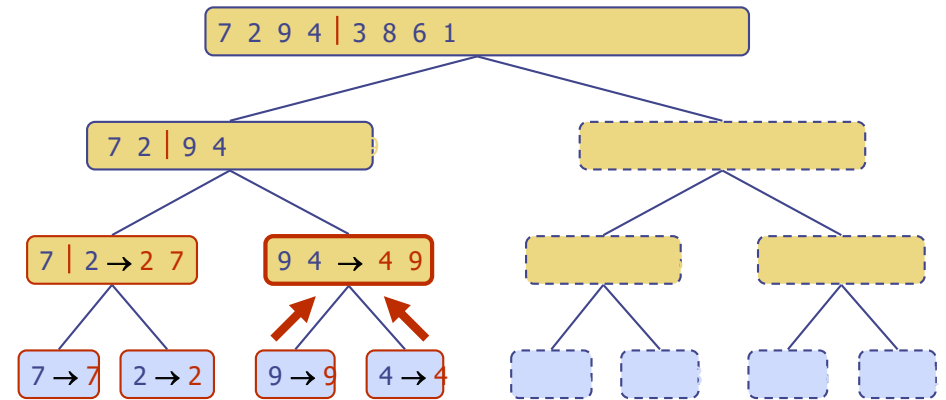
◆ Merge



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Execution Example (cont.)

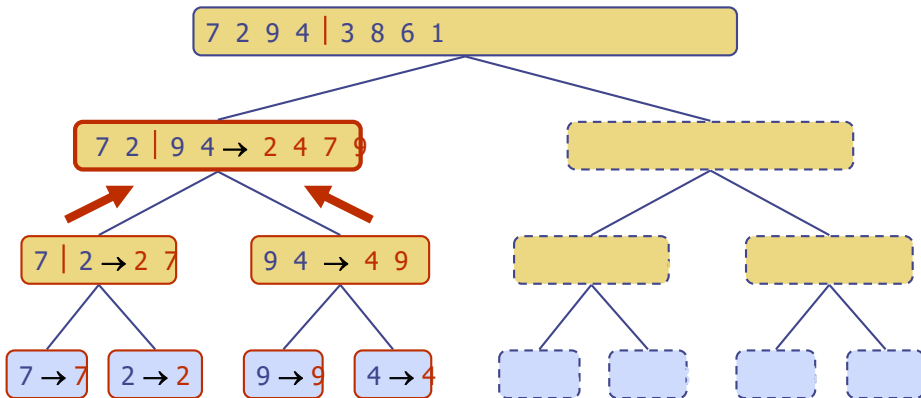
◆ Recursive call, ..., base case, merge



10

Execution Example (cont.)

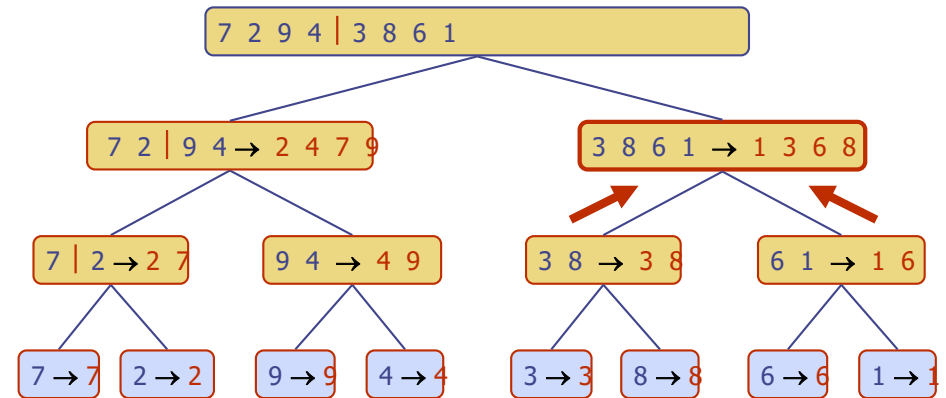
◆ Merge



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Execution Example (cont.)

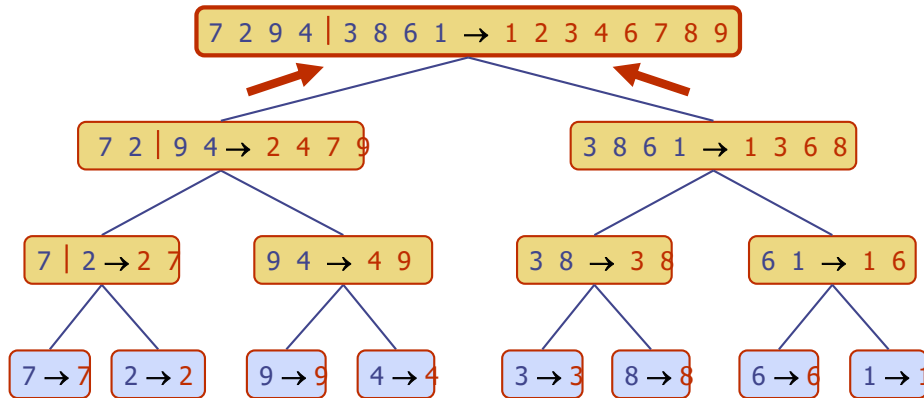
◆ Recursive call, ..., merge, merge



12

Execution Example (cont.)

◆ Merge



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Divide-and-Conquer (§ 10.1.1)

- ◆ **Divide-and-conquer** is a general algorithm design paradigm:
 - **Divide**: divide the input data S in two disjoint subsets S_1 and S_2
 - **Recur**: solve the subproblems associated with S_1 and S_2
 - **Conquer**: combine the solutions for S_1 and S_2 into a solution for S
- ◆ **Merge-sort** is a sorting algorithm based on the divide-and-conquer paradigm
- ◆ Like heap-sort
 - It uses a comparator
 - It has $O(n \log n)$ running time
- ◆ The base case for the recursion are subproblems of size 0 or 1
- ◆ Unlike heap-sort
 - It does not use an auxiliary priority queue
 - It accesses data in a sequential manner (suitable to sort data on a disk)
 - Disk
 - Fast when accessing data sequentially

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Merge-Sort (§ 10.1)

- ◆ Merge-sort on an input sequence S with n elements consists of three steps:

- **Divide**: partition S into two sequences S_1 and S_2 of about $n/2$ elements each
- **Recur**: recursively sort S_1 and S_2
- **Conquer**: merge S_1 and S_2 into a unique sorted sequence

```

Algorithm mergeSort(S, C)
  Input sequence  $S$  with  $n$  elements, comparator  $C$ 
  Output sequence  $S$  sorted according to  $C$ 
  if  $S.size() > 1$ 
     $(S_1, S_2) \leftarrow partition(S, n/2)$ 
    mergeSort( $S_1, C$ )
    mergeSort( $S_2, C$ )
     $S \leftarrow merge(S_1, S_2)$ 
    
```

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Merging Two Sorted Sequences

- ◆ The conquer step of merge-sort consists of merging two sorted sequences A and B into a sorted sequence S containing the union of the elements of A and B
- ◆ Merging two sorted sequences, each with $n/2$ elements and implemented by means of a doubly linked list, takes $O(n)$ time

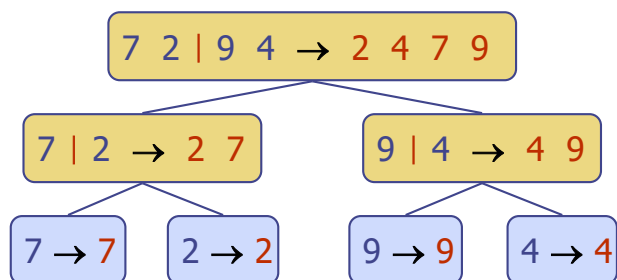
```

Algorithm merge(A, B)
  Input sequences  $A$  and  $B$  with  $n/2$  elements each
  Output sorted sequence of  $A \cup B$ 
   $S \leftarrow$  empty sequence
  while  $\neg A.empty() \wedge \neg B.empty()$ 
    if  $A.front() < B.front()$ 
       $S.addBack(A.front()); A.eraseFront();$ 
    else
       $S.addBack(B.front()); B.eraseFront();$ 
  while  $\neg A.empty()$ 
     $S.addBack(A.front()); A.eraseFront();$ 
  while  $\neg B.empty()$ 
     $S.addBack(B.front()); B.eraseFront();$ 
  return  $S$ 
    
```

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Merge-Sort Tree

- ◆ An execution of merge-sort is depicted by a binary tree
 - each node represents a recursive call of merge-sort and stores
 - ◆ unsorted sequence before the execution and its partition
 - ◆ sorted sequence at the end of the execution
 - the root is the initial call
 - the leaves are calls on subsequences of size 0 or 1



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Another Analysis: Recurrence Equation (1)

- ◆ $t(n)$: the worst-case running time of merge-sort
- ◆ For simplicity, n is a power of 2. Then, we have the following:

$$t(n) = \begin{cases} b & \text{if } n \leq 1 \\ 2t(n/2) + cn & \text{otherwise.} \end{cases}$$

- ◆ How to compute the order of $t(n)$?
- ◆ Applying the equation recursively,

$$\begin{aligned} t(n) &= 2(2t(n/2^2) + (cn/2)) + cn \\ &= 2^2t(n/2^2) + 2(cn/2) + cn = 2^2t(n/2^2) + 2cn. \end{aligned}$$

- ◆ We get the following general equation:

$$t(n) = 2^i t(n/2^i) + icn.$$

- ◆ We stop this when $n/2^i = 1$, i.e., $i = \log n$

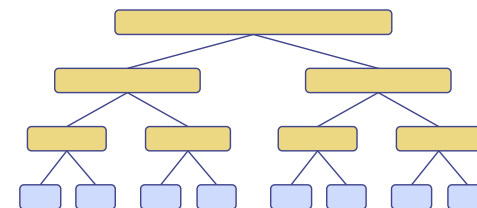
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Analysis of Merge-Sort

- ◆ The height h of the merge-sort tree is $O(\log n)$
 - at each recursive call we divide in half the sequence,
- ◆ The overall amount of work done at the nodes of depth i is $O(n)$
 - we partition and merge 2^i sequences of size $n/2^i$
 - we make 2^{i+1} recursive calls
- ◆ Thus, the total running time of merge-sort is $O(n \log n)$

depth #seqs size

0	1	n
1	2	$n/2$
i	2^i	$n/2^i$
...



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Another Analysis: Recurrence Equation (2)

- ◆ Then, we have the following, and thus we are done.

$$\begin{aligned} t(n) &= 2^{\log n} t(n/2^{\log n}) + (\log n)cn \\ &= nt(1) + cn \log n \\ &= nb + cn \log n. \end{aligned}$$

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Summary of Sorting Algorithms

Algorithm	Time	Notes
selection-sort	$O(n^2)$	<ul style="list-style-type: none">▪ slow▪ in-place▪ for small data sets (< 1K)
insertion-sort	$O(n^2)$	<ul style="list-style-type: none">▪ slow▪ in-place▪ for small data sets (< 1K)
heap-sort	$O(n \log n)$	<ul style="list-style-type: none">▪ fast▪ in-place▪ for large data sets (1K — 1M)
merge-sort	$O(n \log n)$	<ul style="list-style-type: none">▪ fast▪ sequential data access▪ for huge data sets (> 1M)

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Questions?