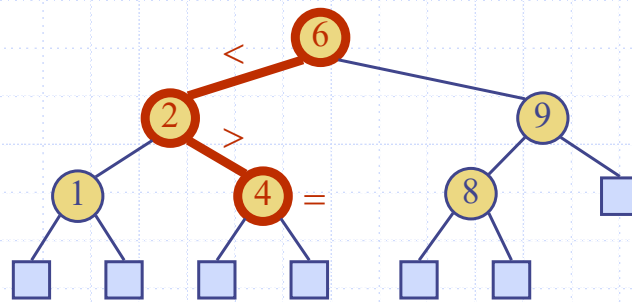


Binary Search Trees



1

Recall: Ordered Maps



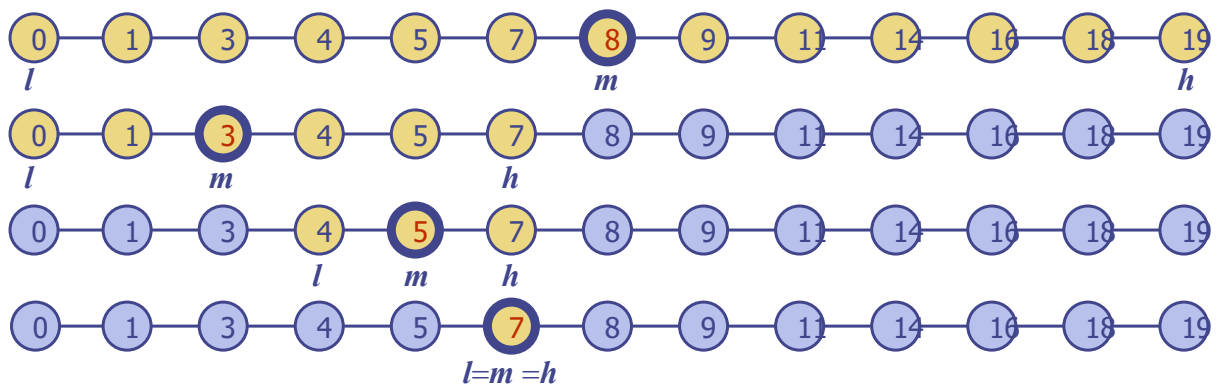
- ◆ Keys come from a total order
- ◆ New operations:
 - Each returns an **iterator** to an entry:
 - **firstEntry()**: smallest key in the map
 - **lastEntry()**: largest key in the map
 - **floorEntry(k)**: largest key $\leq k$
 - **ceilingEntry(k)**: smallest key $\geq k$
 - All return **end** if the map is empty

2

Binary Search

- ◆ Binary search can perform operations **get**, **floorEntry** and **ceilingEntry** on an ordered map implemented by means of an array-based sequence, sorted by key
 - similar to the high-low game
 - at each step, the number of candidate items is halved
 - terminates after $O(\log n)$ steps

- ◆ Example: **find(7)**



3



Search Tables

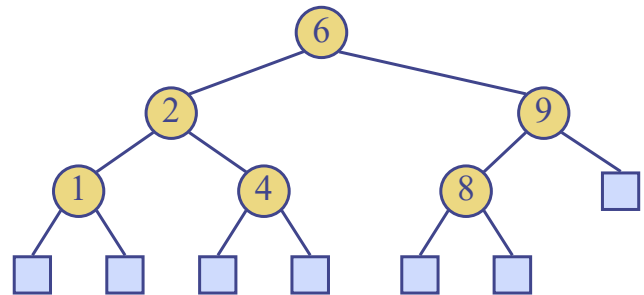
- ◆ A search table is an ordered map implemented by means of a sorted sequence
 - We store the items in an array-based sequence, sorted by key
 - We use an external comparator for the keys (for any arbitrary comparison)
- ◆ Performance:
 - **get**, **floorEntry** and **ceilingEntry** take $O(\log n)$ time, using binary search
 - **get** takes $O(n)$ time since in the worst case we have to shift $n/2$ items to make room for the new item
 - **erase** take $O(n)$ time since in the worst case we have to shift $n/2$ items to compact the items after the removal

4

Binary Search Trees

- ◆ A binary search tree is a binary tree storing keys (or key-value entries) at its internal nodes and satisfying the following property:
 - Let u , v , and w be three nodes such that u is in the left subtree of v and w is in the right subtree of v . We have $key(u) \leq key(v) \leq key(w)$
- ◆ External nodes do **not** store items

- ◆ An inorder traversal of a binary search trees visits the keys in increasing order



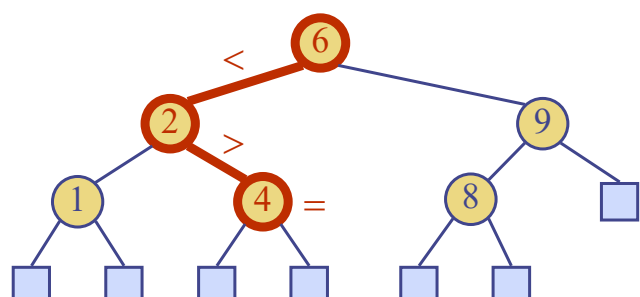
5

Search

- ◆ To search for a key k , we trace a downward path starting at the root
- ◆ The next node visited depends on the comparison of k with the key of the current node
- ◆ If we reach a leaf, the key is not found
- ◆ Example: `get(4)`:
 - Call `TreeSearch(4,root)`
- ◆ The algorithms for `floorEntry` and `ceilingEntry` are similar
- ◆ Recursive

```

Algorithm TreeSearch( $k, v$ )
    if  $v.isExternal()$ 
        return  $v$ 
    if  $k < v.key()$ 
        return TreeSearch( $k, v.left()$ )
    else if  $k = v.key()$ 
        return  $v$ 
    else {  $k > v.key()$  }
        return TreeSearch( $k, v.right()$ )
    
```

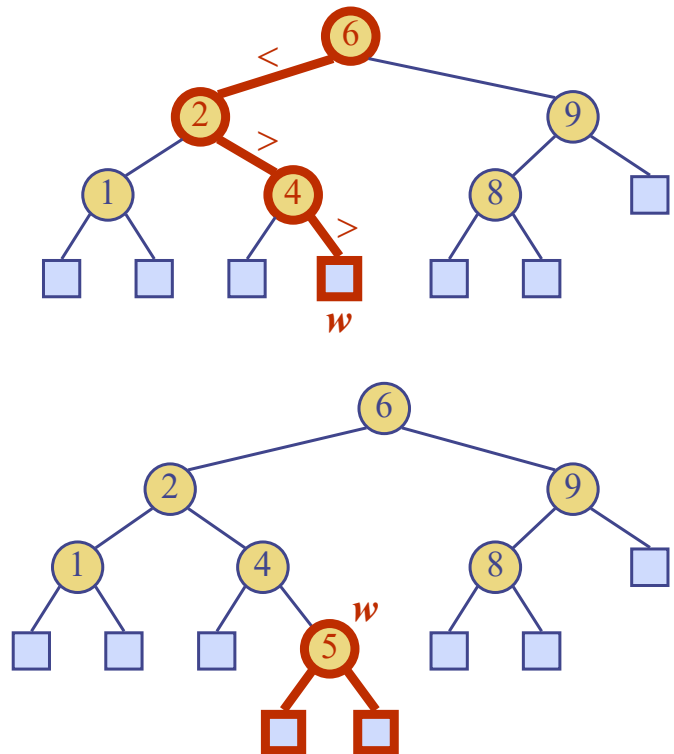


6

Insertion

- ◆ To perform operation `put(k, o)`, we search for key k (using `TreeSearch`)
- ◆ Assume k is not already in the tree, and let w be the leaf reached by the search
- ◆ We insert k at node w and expand w into an internal node

Example: `insert(5)`

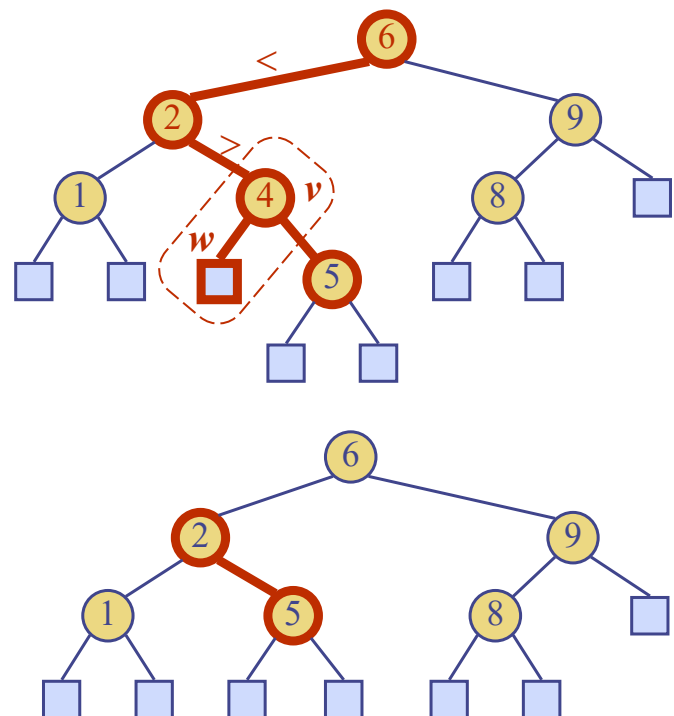


7

Deletion

- ◆ To perform operation `erase(k)`, we search for key k
- ◆ Assume key k is in the tree, and let v be the node storing k
- ◆ Basic method
 - `removeAboveExternal(w)`: removes w and its parent
- ◆ If node v has a leaf child w , we remove v and w from the tree with `removeAboveExternal(w)`
- ◆ What about “remove 1”?

Example: `remove 4`

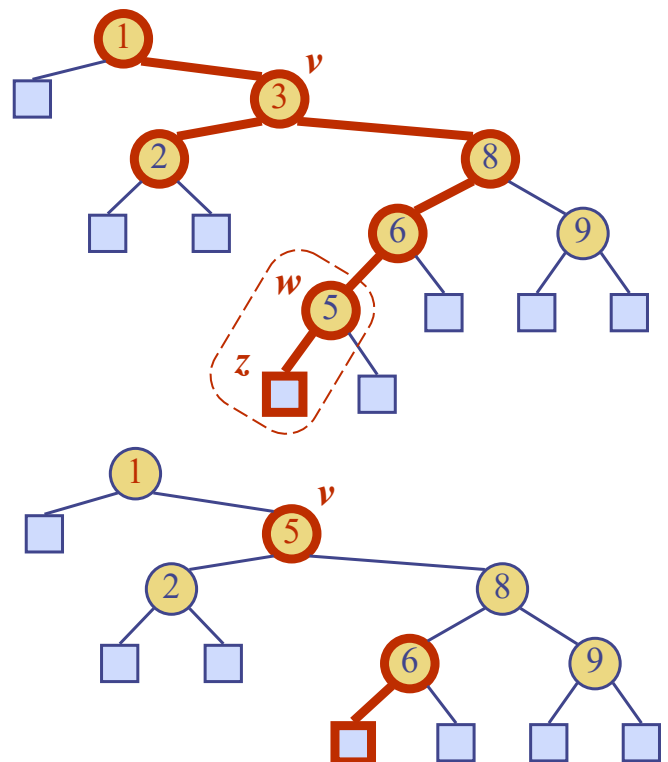


8

Deletion (cont.)

- ◆ Key k to be removed is stored at a node v whose children are both internal
- ◆ 1. Find the internal node w that follows v in an inorder traversal (find the smallest w larger than v)
- ◆ 2. Copy $key(w)$ into node v
- ◆ 3. Remove node w and its left child z (which must be a leaf) by means of operation `removeExternal(z)`
 - Why left child z ?
- ◆ *No other cases?*

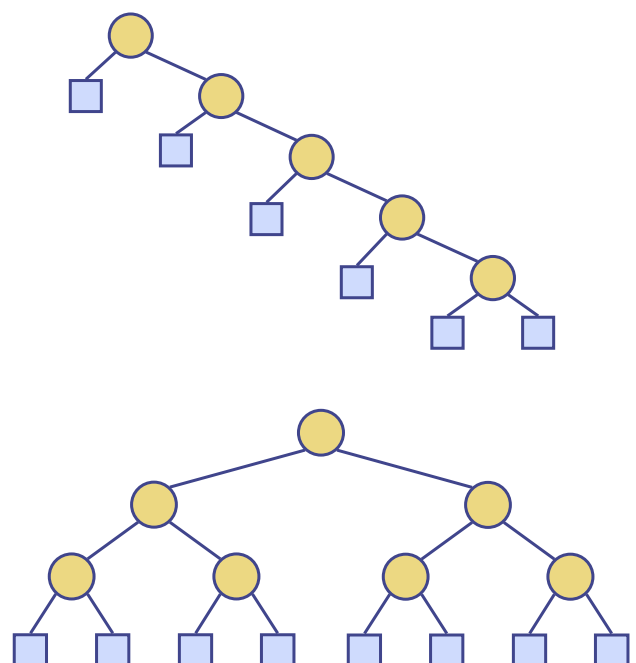
Example: remove 3



9

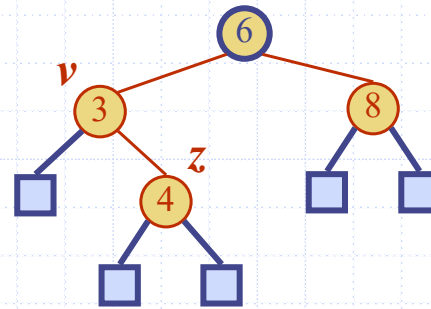
Performance

- ◆ Consider an ordered map with n items implemented by a binary search tree of height h
 - Space: $O(n)$
 - methods `get`, `floorEntry`, `ceilingEntry`, `put` and `erase` take $O(h)$ time
- ◆ The height h is $O(n)$ in the worst case and $O(\log n)$ in the best case
- ◆ Question: Can we find the algorithm with worst-case $O(\log n)$
 - Idea??? **Balancing**



10

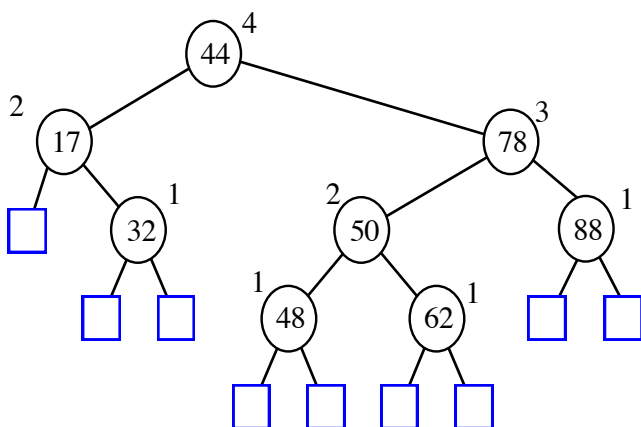
AVL Trees



Adelson-Velskij, G.; E. M. Landis (1962). "An algorithm for the organization of information". *Proceedings of the USSR Academy of Sciences* **146**: 263–266. (Russian) English translation by Myron J. Ricci in *Soviet Math. Doklady*, 3:1259–1263, 1962.

AVL Tree Definition

- ◆ An AVL Tree T is a **binary search tree** with the following property
 - Height-Balance:
For every internal node v of T , the heights of the children of v can differ by at most 1
- ◆ This tree seems to be well-balanced
 - Height: $O(\log n)$



Height of an AVL Tree (1)

◆ **Fact:** The height of an AVL tree storing n keys is $O(\log n)$.

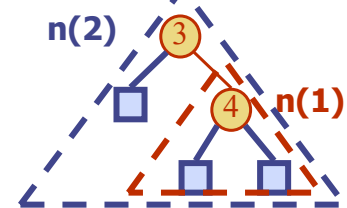
◆ **Proof**

- $n(h)$: the minimum number of internal nodes of an AVL tree of height h .
- Easily see that $n(1) = 1$ and $n(2) = 2$
- For $h > 2$, an AVL tree of height h and the minimum number of nodes contains (i) the root node, (ii) one AVL subtree of height $h-1$ and (iii) another AVL subtree of height $h-2$.
- That is, $n(h) = 1 + n(h-1) + n(h-2)$

◆ Knowing $n(h-1) > n(h-2)$, we get $n(h) > 2n(h-2)$. So

$$n(h) > 2n(h-2), n(h) > 4n(h-4), n(h) > 8n(h-6), \dots \text{ (by induction),}$$

$$n(h) > 2^i n(h-2i)$$



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Height of an AVL Tree (2)

◆ $n(h) > 2n(h-2), n(h) > 4n(h-4), n(h) > 8n(h-6), \dots$ (by induction),
 $n(h) > 2^i n(h-2i)$ (for any integer i , such that $h-2i \geq 1$)

◆ We pick i so that $h-2i = 1$ or 2 (base case)

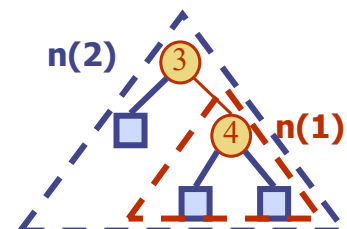
$$i = \left\lceil \frac{h}{2} \right\rceil - 1.$$

◆ Then, we have

$$\begin{aligned} n(h) &> 2^{\lceil \frac{h}{2} \rceil - 1} \cdot n\left(h - 2\left\lceil \frac{h}{2} \right\rceil + 2\right) \\ &\geq 2^{\lceil \frac{h}{2} \rceil - 1} n(1) \\ &\geq 2^{\frac{h}{2} - 1}. \end{aligned}$$

◆ Taking logarithms: $h < 2 \log n(h) + 2$

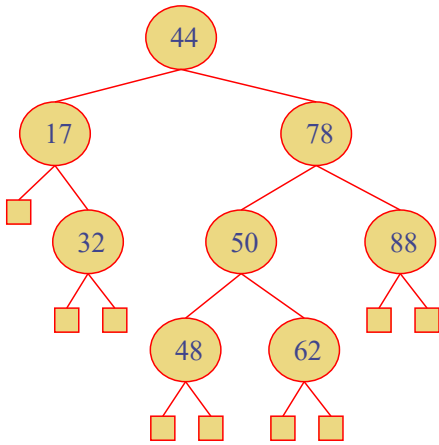
◆ Thus, the height of an AVL tree is $O(\log n)$



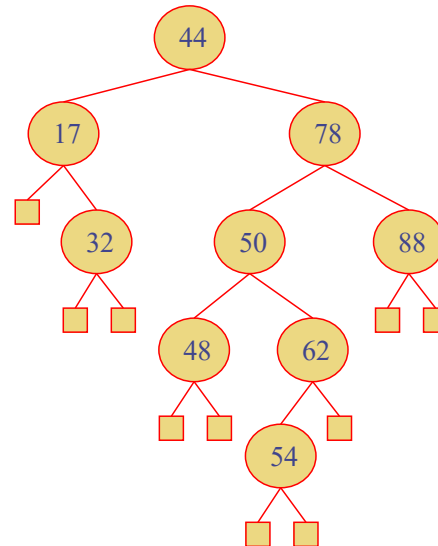
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Insertion

- ◆ Insertion is as in a binary search tree
- ◆ Always done by expanding an external node.
- ◆ Example of insertion 54. What's the problem?



before insertion 54



after insertion 54

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Rebalancing Needed

- ◆ How should we do this?
 - (1) Take some examples
 - (2) Find difference cases
 - (3) Make each sub-algorithm for each case
 - (4) Make an entire algorithm
 - (5) Run it with some inputs
 - (6) Find out it is not working perfectly, and say “What the hell is this?” “How should I do?”



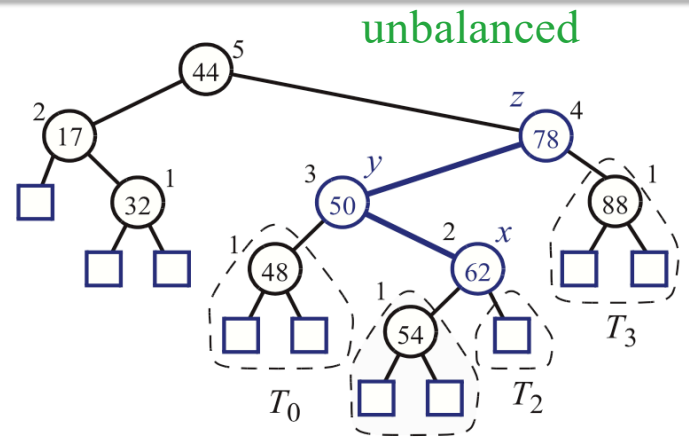
- ◆ Lessons

- Let's summarize them later

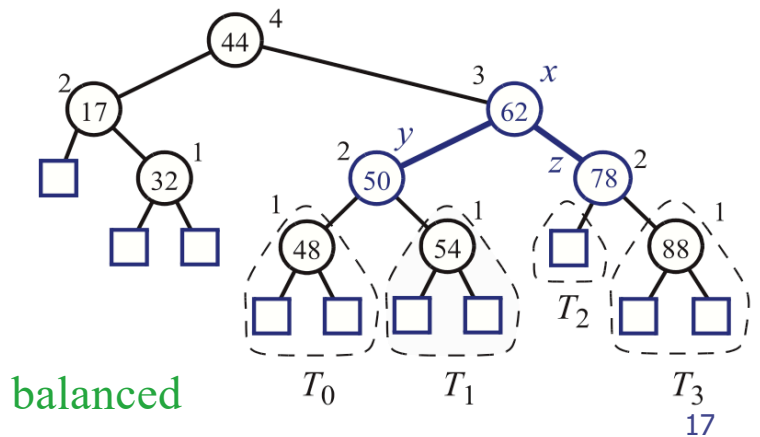
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Rebalancing Example: Insertion of $w=54$

- ◆ “Search-and-Repair” strategy
- ◆ z : first node we encounter in going up from w toward the root such that z is unbalanced
- ◆ y : the child of z with higher height (note that y must be an ancestor of w)
- ◆ x : the child of y with higher height (there cannot be a tie and node x must be an ancestor of w)



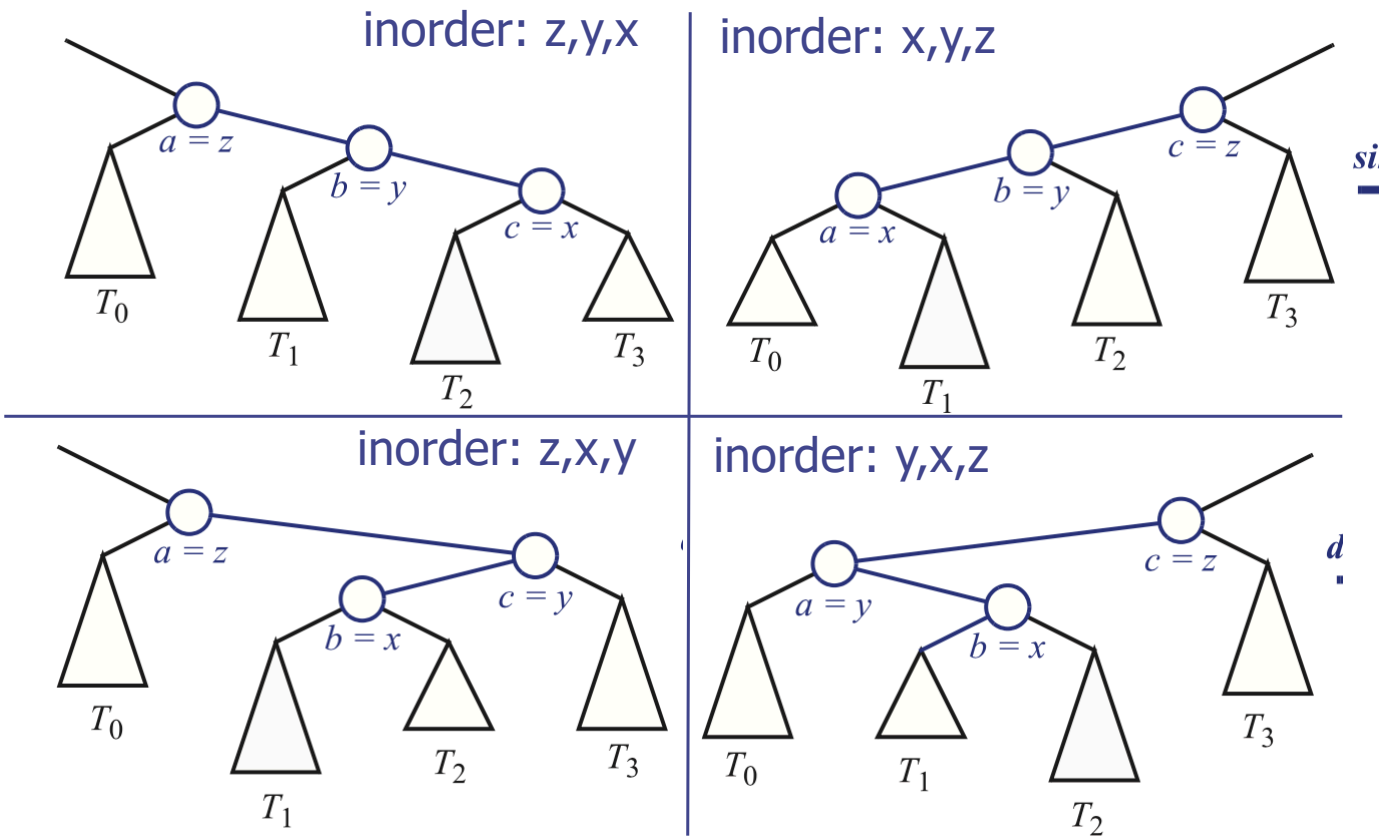
- ◆ What are we doing for balancing?
- ◆ Can we do this systematically?
- ◆ What are other cases?



Please remember the notations! z, y, z

- ◆ z : first node we encounter in going up from w toward the root such that z is unbalanced
 - “ w 에서 위로 쪽 올라가서, balance깨지는 첫 놈”
- ◆ y : the child of z with higher height
 - “그 놈의 자녀 중 키가 큰 놈”
- ◆ x : the child of y with higher height
 - “그 키 큰 자녀의 자녀(손주) 중 키가 큰 놈”
- ◆ Rename x, y, z as a, b, c so that a precedes b and b precedes c in “inorder traversal”
 - We can make many combinations

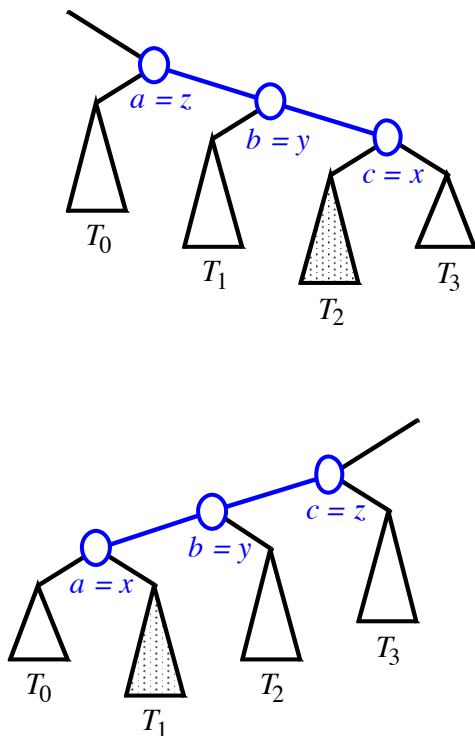
4 Combinations



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Restructuring (as Single Rotations)

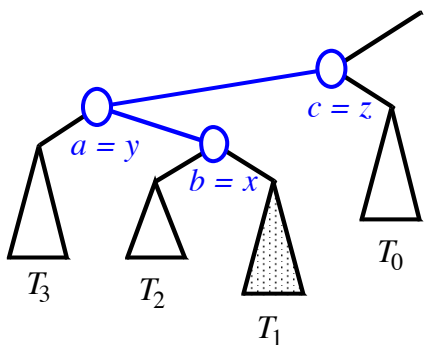
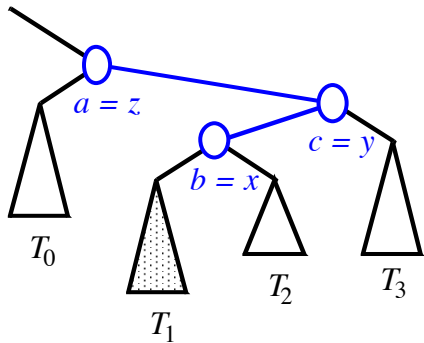
◆ Single Rotations:



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Restructuring (as Double Rotations)

◆ double rotations:

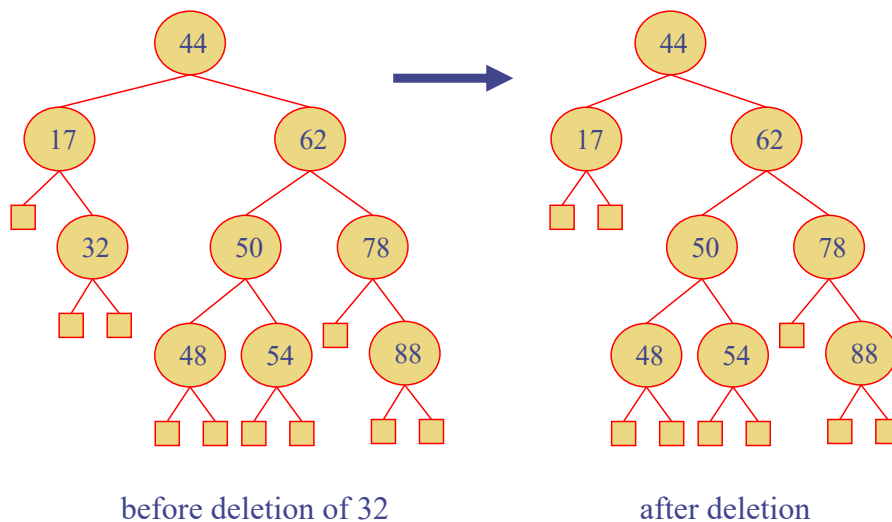


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Removal

◆ Removal begins as in a binary search tree, which means the node removed (after copying the in-order successor) will become an empty external node. Its parent, w, may cause an imbalance.

◆ Example:



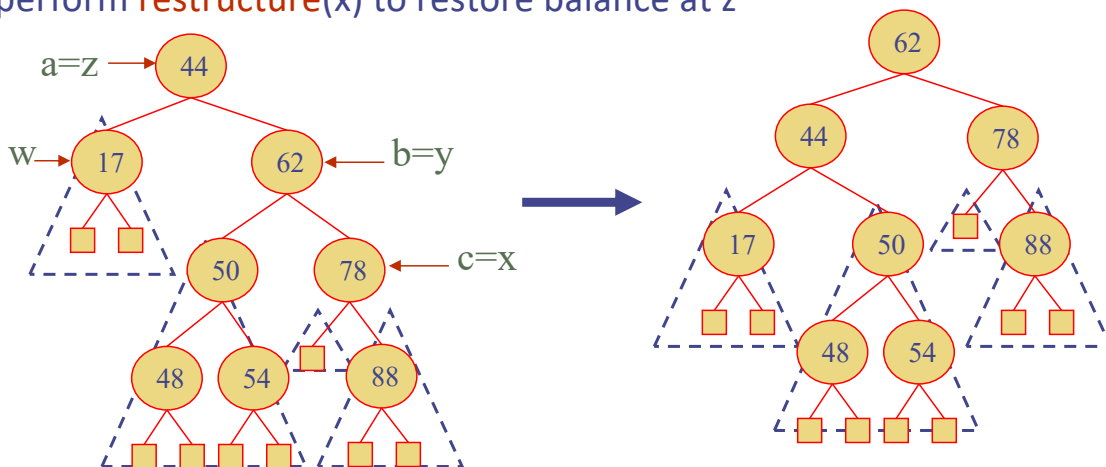
before deletion of 32

after deletion

22

Rebalancing after a Removal

- ◆ Let z be the **first unbalanced** node encountered while travelling up the tree from w . Also, let y be the child of z with the larger height, and let x be the child of y with the larger height
- ◆ We perform **restructure**(x) to restore balance at z

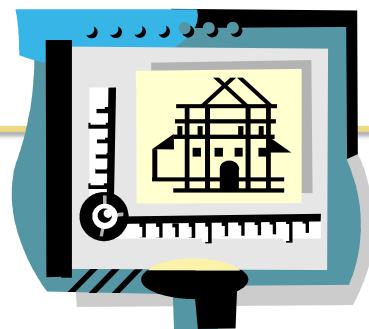


- ◆ What happens if z is an internal node, not the root?
- ◆ As this restructuring may upset the balance of another node higher in the tree, we must continue checking for balance until the root of T is reached

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AVL Tree Performance

- ◆ a single restructure takes $O(1)$ time
 - using a linked-structure binary tree
- ◆ **find** takes $O(\log n)$ time
 - height of tree is $O(\log n)$, no restructures needed
- ◆ **put** takes $O(\log n)$ time
 - initial find is $O(\log n)$
 - Restructuring up the tree, maintaining heights is $O(\log n)$
- ◆ **erase** takes $O(\log n)$ time
 - initial find is $O(\log n)$
 - Restructuring up the tree, maintaining heights is $O(\log n)$



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Recall: Rebalancing Needed

◆ How should we do this?



- (1) Take some examples
- (2) Find difference cases
- (3) Make each sub-algorithm for each case
- (4) Make an entire algorithm
- (5) Run it with some inputs
- (6) Find out it is not working perfectly, and say “What the hell is this?” “How should I do?”

◆ Lessons

- Sometimes, we need to do case-by-case handling to complete the algorithm
- People often rely on “Half-assed (대충) algorithm design first “ and “Complete it using example inputs”. Not recommended.
 - ◆ Same as “Roughly make the code, and debug it later”. Bad coding behavior

Questions?